

Non-periodic bifurcations for surface diffeomorphisms

Vanderlei Horita, Nivaldo Muniz and Paulo Rogério Sabini

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Abstract

We prove that a “positive probability” subset of the boundary of the set of hyperbolic (Axiom A) surface diffeomorphisms with no cycles \mathcal{H} is constituted by Kupka-Smale diffeomorphisms: all periodic points are hyperbolic and their invariant manifolds intersect transversally. Lack of hyperbolicity arises from the presence of a tangency between a stable manifold and an unstable manifold, one of which is *not* associated to a periodic point. All these diffeomorphisms that we construct lie on the boundary of the same connected component of \mathcal{H} .

1 Introduction

One of the most challenging problems in Dynamical Systems theory is to understand how the stability breaks down under small changes of the evolution law. We say that a system is *stable* if there exists a neighborhood where all systems are topologically conjugated to it. It is a well known fact that hyperbolic (Axiom A) systems with no cycles are stable. A very successful method to study the breakdown of hyperbolicity is by considering parametrized families of systems starting inside the hyperbolic domain

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and describing the ways how hyperbolicity is destroyed when the parameter varies. Many authors have studied this problem following this approach, see [4, 5, 6, 7, 10, 12, 14, 15, 16, 17, 18], just to mention a few references. In all these works the mechanism responsible for the break down of stability involves periodic orbits; indeed, it falls in one of the following two types :

- (NH) *there exists an unique periodic orbit that is non-hyperbolic*, and it is either a saddle-node (one eigenvalue equal to 1), a period-doubling (one eigenvalue equal to -1), or a Hopf orbit (two complex conjugate eigenvalues with norm 1);
- (NT) all the periodic orbits are hyperbolic, but *there exists an unique non-transverse intersection between some stable and some unstable manifold of periodic orbits*; this intersection is quasi-transverse (codimension 1).

Newhouse and Palis in [11] conjectured that (NH) and (NT) are the generic mechanism for the collapse of hyperbolicity along families of diffeomorphisms starting from a Morse-Smale diffeomorphism. That is, generically, Morse-Smale diffeomorphisms should remain hyperbolic for as long as they remain Kupka-Smale. Newhouse, Palis, and Takens in [13] show that this conjecture is true when the limit set (the set of forward and backward limit points) is still finite at bifurcation parameter : generically the bifurcating diffeomorphisms is of type (NH) or (NT). To the best of our knowledge there has been essentially no other significant progress in the direction of this conjecture.

Motivated by the advances in the theory of Hénon-like dynamics, Bonatti, Viana suggested that the problem should be approached from a probabilistic point of view, and, in this context, the conclusion should be opposite. They conjectured that there exists a subset of the boundary of the set of hyperbolic systems which is formed by Kupka-Smale diffeomorphisms and has positive measure, in some natural sense, so that (NH) and (NT) should not account for *almost all* transitions to non-hyperbolicity. The conjecture was proved by the present authors [7] in the setting of non-invertible circle maps. In the present work we prove that the Bonatti-Viana conjecture is also true for surface diffeomorphisms.

In all what follows M will denote a surface and \mathcal{H} the set of hyperbolic (Axiom A) systems with the no-cycle condition defined on M .

Theorem 1. There is an open set \mathcal{U} of 2-parameter families $(f_{a,\theta})_{a,\theta}$ of surface diffeomorphisms such that for a positive set \mathcal{A} of parameters a

- (a) for some $\theta^* = \theta^*(a)$, the map f_{a,θ^*} has a heteroclinic (cubic) tangency between invariant manifolds, one of which is not associated to a periodic point;
- (b) all f_{a,θ^*} belong to the boundary of \mathcal{H} .
- (c) all periodic points of f_{a,θ^*} are hyperbolic;
- (d) all intersections between stable and unstable manifold of periodic points of f_{a,θ^*} are transverse;

In fact, the diffeomorphisms f_{a,θ^*} that we construct are in the boundary of the same connected component of \mathcal{H} (their lack of hyperbolicity follows from item (a)). The corresponding property for circle maps could not be proved in [7]. We present here a proof of that fact, thus strengthening Theorem A in that paper.

Theorem 2 (Theorem A of [7] revisited). There exists an open set \mathcal{U} of 2-parameters families $(f_{a,\theta})_{a,\theta}$ of maps of the circle such that for some $\theta_* = \theta_*(a)$, the map f_{a,θ_*} has a (cubic) critical point. Moreover, for a positive Lebesgue measure set \mathcal{A} of parameters a :

- (1) there exists a continuous curve $a(\theta)$ in the parameter space (a, θ) , with $a(\theta_*) \in \mathcal{A}$, such that $f_{a(\theta),\theta}$ belongs to the interior of the uniformly hyperbolic (expanding) domain for every $\theta < \theta_*$;
- (2) all periodic points of f_{a,θ_*} are hyperbolic (expanding), and no critical point is pre-periodic.

The diffeomorphisms that we consider in Theorem 1 are (strongly) dissipative, indeed we view them as a kind of singular perturbation of the cubic maps [7] in much the same way as Hénon-like diffeomorphisms are treated as perturbations of quadratic maps of the interval in works as [2], [9], see Remark 3.2.

We adapt techniques developed by Benedicks, Carleson [2] and Mora, Viana [9] in those papers to obtain exponential growth of the derivative in some direction. An important new difficulty arises from the fact that the tangency (criticality) for the “unperturbed” circle maps is degenerate (cubic). This makes it specially tricky to detect and control tangencies for the kind of singular perturbation that we deal with, all the more so because

we also have to deal with stable manifolds not associated to any periodic point. A key ingredient to circumvent this difficulty is to establish a good notion of critical points and appropriated control of degeneration of angles between tangent direction of invariant manifolds.

The core of this paper comes from Paulo Sabini's doctoral thesis. We considered it worthwhile to work on that initial text, sharpening the results and improving the arguments, and that led to the present joint paper. Sadly, during that work, Paulo passed away, at the age of 33. We miss him deeply.

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2 Proof of Theorem 2

Proof. The claim is that the families present in Theorem A of [7] satisfy both items. The second one has already been proved so we just need to prove item (1).

Recall the definition of the families in [7]. We can suppose, by reparametrizing those families, that $\theta_*(a) = 0$ for all a . The construction of the set \mathcal{A} is based on the method present in [1] for quadratic maps. Roughly speaking, we exclude parameters a that infringe a given restriction of the loss of expansion due to the proximity of a point that we call the *critical point*. Although in our context we do not have a critical point for negative θ , we introduce a notion that has the same role. In [7], for each fixed parameter $\theta \leq 0$ we perform an exclusion of parameters a in order to obtain a positive measure subset Ω_θ of parameters a such that the orbit of the critical point presents expansion of the derivative. In fact, we do not take into account the fact that our *critical point* is not a true criticality (zero derivative). At the end of the construction we obtain a set Ω_θ with empty interior, but positive measure. Here, we intend to revisit those techniques in a more accurate way for showing that it is possible to get Ω_θ as an union of a finite number of intervals of parameters. The reason why this is expected is because after a certain step $n = n(\theta)$ of the construction we do not have to exclude parameters anymore since the derivative is uniformly bounded away from zero.

The exclusions of a -parameters for a fixed $\theta < 0$ take place for two reasons: the first one is to control the recurrence of returns of the critical point,

and the second one is to avoid too frequent recurrence to the critical region $(a - \delta, a + \delta)$. The heuristic to circumvent these two mechanisms of exclusion of parameters follows. Let $\varepsilon = f'_{a,\theta}(a) > 0$ be the derivative of $f_{a,\theta}$ at the critical point a . By construction, a is taken close to the distinct pre-image \bar{a} of the fixed point p of the initial map f , see [7, Section 1.4]. We address the reader to follow this discussion in parallel to Section 2 of [7]. In particular in the sequel c stands for the expansion of derivatives stated therein. Let J be a small neighborhood of p such that $\sup\{f'_{a,\theta}(x): x \in J\} \geq \sigma > 1$. Fix an integer $m_0 > 0$ satisfying $\varepsilon \cdot \sigma^{m_0} > e^{\tilde{c}m_0}$, for some constant $\tilde{c} > 0$. We can suppose (by reducing η in Proposition 2.3 of [7], if necessary), that $f_{a,\theta}^j(a) \in J$ for every $1 \leq j \leq m_0$. We can even suppose that m_0 is large enough implying $\tilde{c} > c$, since $\sigma > e^c$. By continuity, there exists $\zeta > 0$ such that for every $1 \leq j \leq m_0$, we have

$$f_{a,\theta}^j(x) \in J \quad \text{for every } x \in (a - \zeta, a + \zeta).$$

Let us fix $\hat{c} < c$ with $|\hat{c} - c| \ll 1$ and let $\tilde{n} \geq 1$ be such that $e^{-\tilde{n}\alpha} < \zeta$ and $\varepsilon e^{c\tilde{n}} \geq e^{\hat{c}(\tilde{n}+1)}$. Let $\omega \in \Omega_{\theta,\tilde{n}}$ and Let n_k be the first return situation for ω after \tilde{n} .

$$|(f_{a,\theta}^j)'(f_{a,\theta}(a))| \geq e^{cj}, \quad \text{for } 1 \leq j \leq n_k - 1. \quad (1)$$

$$|(f_{a,\theta}^j)'(f_{a,\theta}(a))| \geq \varepsilon e^{c(j-1)} e^{\tilde{c}(j-n_k)} \geq e^{\hat{c}j}, \quad \text{for } n_k \leq j \leq n_k + m_0 - 1. \quad (2)$$

$$|(f_{a,\theta}^j)'(f_{a,\theta}(a))| \geq e^{cn_k} e^{\tilde{c}m_0} \geq e^{c(n_k+m_0)} \quad \text{for } j = n_k + m_0. \quad (3)$$

$$|(f_{a,\theta}^j)'(f_{a,\theta}(a))| \geq e^{cj} \quad \text{for } n_k + m_0 + 1 \leq j < n_{k+1}. \quad (4)$$

Hence every return situation after \tilde{n} can be dealt with without exclusions for $(BA)_n$ violations and every parameter a not excluded up to that time will satisfy:

$$|(f_{a,\theta}^j)'(f_{a,\theta}(a))| \geq e^{\hat{c}j} \quad \text{for } j \geq 1$$

Thus,

$$\Omega_\theta = \lim_{n \rightarrow \infty} \Omega_{\theta,n} = \Omega_{\theta,\tilde{n}}.$$

Recall that for each n the set $\Omega_{\theta,n}$ is the union of a finite number of intervals of parameters a , see [7, Section 4]. So, in each vertical line over θ , $-1 \leq \theta \leq 0$, we have a finite union of intervals (see Figure 1). Moreover, for θ close to -1 , we do not need to exclude any parameter, because the initial map is uniformly expanding. When θ increases, the derivative decreases in

the perturbation region and some exclusion of parameters is necessary due the loss of expansion. Increasing θ we have to exclude more and more intervals of parameters a . Since the whole structure varies continuously with θ , we have *legs* in the (a, θ) -plane such that all maps outside them are uniformly expanding (see Figure 1).

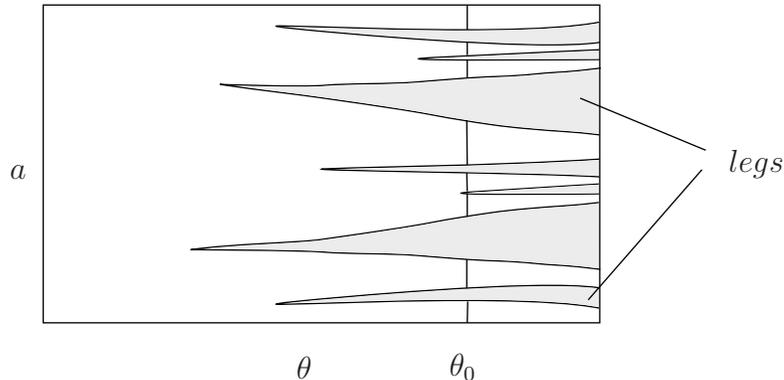


Figure 1: Parameter space for a fixed n

As we see above, fixed a negative θ_0 close to 0 there is $\tilde{n}(\theta)$ (which can be supposed increasing with θ) such that for all $n \geq \tilde{n}$ we do not need to exclude more parameters of $\Omega_{\theta,n}$, for every $\theta < \theta_0$. Thus, the parameters space do not change in the rectangle $[-1, \theta_0] \times [a - \eta, a + \eta]$.

Finally, when θ_0 goes to 0 and n tends to infinity, for each $a \in \mathcal{A}$ we have a continuous path

$$a(\cdot) : [-1, 0] \rightarrow [-1, 0] \times [a - \eta, a + \eta]$$

inside the parameter space such that each corresponding map is uniformly expanding. This completes the proof of Theorem 2. \square

3 The families

Here we describe the families which are object of Theorem 1. In the following sections we prove that they satisfy the claims.

Let f be a C^r -diffeomorphism, $r \geq 3$ defined on a compact boundaryless surface M having a *strongly dissipative non trivial minimal attractor* Λ , that is, Λ is a minimal, (uniformly) hyperbolic, transitive (it has a dense orbit),

and attracting set ($\Lambda = \bigcap_{n \in \mathbb{N}} f^n(\mathcal{U})$ for some neighborhood \mathcal{U} of Λ) where the contraction of the stable bundle is much stronger than the expansion of the unstable bundle in a sense to be made precise in a little while. So, $\Lambda = \overline{W^u(P)}$ for every periodic point P of f .

Let P and Q be periodic points in Λ with distinct orbits, and let $q \in \Lambda$ be a heteroclinic point such that $q \in W^u(P) \cap W^s(Q)$. For simplicity we suppose that both P and Q are fixed points of f .

Assuming a finite number of nonresonance properties on the eigenvalues of P and Q we can assume that f is linearizable at P and Q and that the linearizing coordinates vary continuously on a small C^3 -neighborhood \mathcal{V} of f , see [19], [4], and [6] for details. For every $g \in \mathcal{V}$, we denote (x_i, y_i) , $i = 1, 2$ such coordinates on neighborhoods \mathcal{U}_i of P and Q , respectively (we omit the dependence of the coordinates on the diffeomorphism, for simplicity of notation), see Figure 2.

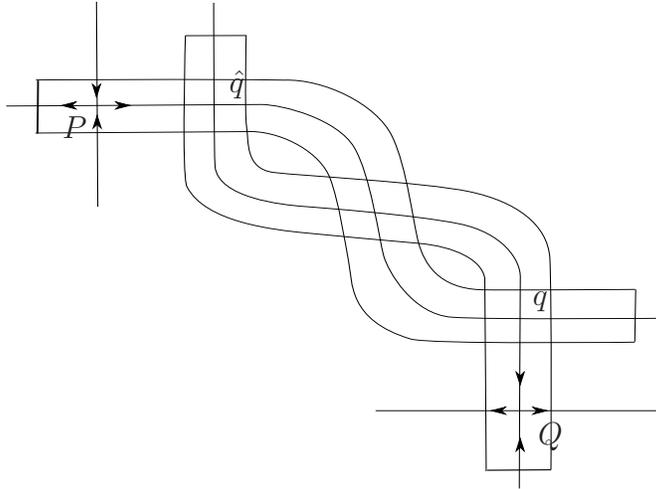


Figure 2: Linearizing coordinates

In this system of coordinates, points $z = (x_1(z), y_1(z))$ in $W_{loc}^s(P)$ (resp. in $W_{loc}^u(P)$) are such that $x_1 = 0$ (resp. $y_1 = 0$), and similarly points $z = (x_2(z), y_2(z))$ in $W_{loc}^s(Q)$ (resp. in $W_{loc}^u(Q)$) are such that $x_2 = 0$ (resp. $y_2 = 0$). By extending the neighborhoods \mathcal{U}_i , if necessary, we can suppose that $\mathcal{U}_1 \cap \mathcal{U}_2$ contains q and $\hat{q} = f^{-1}(q)$. The previous systems of coordinates (x_i, y_i) define in a neighborhood V of q and \hat{V} of \hat{q} , respectively, coordinates (x, y) and (\hat{x}, \hat{y}) , where x and \hat{x} are given by x_2 , and y and \hat{y} are given by

y_1 . In V , the expression of any diffeomorphism $g \in \mathcal{V}$ in these coordinates is linear:

$$x(g(z)) = \sigma_1 \cdot \hat{x}(z) \quad \text{and} \quad y(g(z)) = \lambda_2 \cdot \hat{y}(z),$$

where λ_1 and σ_1 (resp. λ_2 and σ_2) are eigenvalues of P , (resp. Q). It follows from the assumption of strong dissipativeness that $|\lambda_i| \ll 1 < |\sigma_i|$. Let us write $\lambda_2 = b$ in analogy to parameters of Hénon-like families ($b \ll 1$). For simplicity of notation, let us denote both coordinates on \hat{V} and V as (x, y) .

We consider a 2-parameter C^r -family $\tilde{f}_{a,\theta} : M \rightarrow M$, $a \in [-\eta, \eta]$ and $\theta \in [-\eta, \eta]$ as follows.

- (H₁) For every a , the map \tilde{f}_{a,θ_0} is C^r -close to f (and so it is uniformly hyperbolic).
- (H₂) There is an open rectangle $R_0 \subset \hat{V}$ containing \hat{q} such that, for each a and θ , the maps $\tilde{f}_{a,\theta}$ and f are C^r -close outside R_0 .

We choose $\delta > 0$ sufficiently small such that the square $R_\delta = [-\delta, \delta] \times [-\delta, \delta]$ centered in \hat{q} is contained in R_0 , see also Section 5.1.1. We write $S = \tilde{f}_{a,\theta_0}(R_\delta)$. Let us assume that $\eta > 0$ small enough in order to have $q + (a, 0) \in S$, for every $a \in [-\eta, \eta]$.

- (H₃) We deform \tilde{f}_{a,θ_0} inside R in such a way that $\tilde{f}_{a,\theta}$ has local form in R_δ given by

$$\Phi_{a,\theta}(x, y) = (a + \sigma_1 y + x(-A_1 \theta + B_1 x^2 + C_1 y^2), -bx + y(-A_2 \theta + B_2 x^2 + C_2 y^2)),$$

where A_i, B_i, C_i positive constants with $A_2, B_2, C_2 \leq Kb$, for some constant $K > 0$. See Figure 3.

- (H₄) We choose $B_1 \geq C_1 \geq 4\sigma_1 \delta^{-2} \geq 4A_1 > 0$ and $C_1 \leq 5\sigma_1 \delta^{-2}$ (see Remark 3.1 and Section 5.1.1), such that for every $z \in R_0 \setminus R_\delta$ and all norm-1 vector $v = (v_1, v_2)$ with $\text{slope}(v) = |v_2| / |v_1| < (1/10)$ we have

- $\text{slope}(D\tilde{f}_{a,\theta}(z) \cdot v) \leq 1/10$; and

- $\|D\tilde{f}_{a,\theta}(z) \cdot v\| > \sigma_0 > 1$,

for all $|a| < \eta$ and $|\theta| < \delta^2$. (See Remark 3.1).

in a curve that makes an angle with the vertical direction that decreases when θ increases. When $\theta = \theta^*(a)$, this curve tangencies the vertical direction at $q+(a, 0)$. Although the vertical direction has no dynamical meaning, if there are directions of a contractive bundle that are almost vertical defined during all process then the 1-parameter family unfolds a cubic tangency between the unstable manifold of P and a stable manifold of some point. Nevertheless, there are no reasons for the existence of those contractive direction during all the process (and, in general, it seems that they do not exist). An additional problem is to determine if those direction, when exist, are not associated to a periodic point. After overwhelm these two steps, it remains to show that this is the first bifurcation of the family.

Remark 3.1. Let us comment on the compatibility of assumption (H_4) with our construction. Given a norm-1 vector $v = (v_1, v_2)$ with $\text{slope}(v) \leq 1/10$ and $z \in \partial R$, we have

$$\text{slope } D\Phi_{a,\theta}(z) \cdot v < 1/15$$

and

$$\|D\Phi_{a,\theta}(z) \cdot v\| > 2.$$

Proof. Given $z = (x, y)$, from (H_3) , we have

$$\begin{aligned} D\Phi_{a,\theta}(z) \cdot v &= ((-A_1\theta + 3B_1x^2 + C_1y^2)v_1 + (\sigma_1 + 2C_1xy)v_2, \\ &\quad (-b + 2B_2xy)v_1 + (-A_2\theta + B_2x^2 + 3C_2y^2)v_2). \end{aligned} \quad (5)$$

For some positive constant \hat{K} ,

$$|(-b + 2B_2xy)v_1 + (-A_2\theta + B_2x^2 + 3C_2y^2)v_2| \leq \hat{K}b. \quad (6)$$

Since $\|v\| = 1$ and $|\text{slope}(v)| \leq 1/10$ we get $|v_1| > 9/10$. Moreover, from $|\theta| < \delta^2$ we obtain

$$\begin{aligned} |(-A_1\theta + 3B_1x^2 + C_1y^2)v_1 + (\sigma_1 + 2C_1xy)v_2| &\geq \\ &\geq |v_1|[-A_1|\theta| + 3B_1x^2 + C_1y^2 - (\sigma_1 + 2C_1|xy|)|v_2/v_1|] \\ &\geq (9/10)(-A_1\delta^2 + 3B_1x^2 + C_1y^2 - (\sigma_1 + 2C_1|xy|)(1/10)). \end{aligned}$$

Furthermore points $(x, y) \in \partial R$ have either $|x| = \delta$ or $|y| = \delta$, then as $B_1 \geq C_1$,

$$\begin{aligned} |(-A_1\theta + 3B_1x^2 + C_1y^2)v_1 + (\sigma_1 + 2C_1xy)v_2| &\geq \\ &\geq (9/10)[-A_1\delta^2 + C_1\delta^2 - (\sigma_1 + 2C_1\delta^2)/10] \\ &\geq (9/10)[- \sigma_1 + 4\sigma_1 - (11/10)\sigma_1] > 2\sigma_1. \end{aligned}$$

Then, from (5), (6), and last estimate, we obtain

$$|\text{slope}(D\Phi_{a,\theta}(z) \cdot v)| \leq \frac{\hat{K}b}{2\sigma_1} < 1/15.$$

and

$$\|D\Phi_{a,\theta}(z) \cdot v\| \geq 2\sigma_1 > 2.$$

We conclude the proof of the remark. \square

The dynamics outside R_0 is unchanged (so hyperbolic) for every $\tilde{f}_{a,\theta}$, by (H_2) . Thus, it is possible to define $\tilde{f}_{a,\theta}$ in $R_0 \setminus R$ as in condition (H_4) .

Our results apply to every family $(f_{a,\theta})_{a,\theta}$ in a small C^r -neighborhood \mathcal{U} of $(\tilde{f}_{a,\theta})_{a,\theta}$.

Related to this setting of cubic tangencies, in [4, 6], the authors have constructed codimension-3 submanifolds (respectively, codimension-2 submanifolds) of the border of the set of Anosov C^r -diffeomorphisms of the torus \mathbb{T}^2 (respectively, surface diffeomorphisms with basic set different of all surface) corresponding to existence of a cubic tangency between the stable and unstable manifolds of a pair of periodic points. Roughly speaking, they deform a family of diffeomorphisms in a neighborhood of a heteroclinic point in order to create a tangency. During all the process the family remains Anosov. Those families can be adapted to our context by considering a parameter a defining where the tangency with the vertical direction is being created (in those context stable directions of periodic saddles correspond to the vertical direction). See Figure 3.

Let us point out some distinguishing characteristics of the present setting. The bifurcation in [4, 6] are of (NT) type, i.e. the lack of hyperbolicity is due to the presence of a non-transverse intersection of invariant manifolds of periodic points. Since the region of perturbation does not contain none of the periodic points P and Q , the arc of $W^u(P)$ (respectively $W^s(Q)$), from P through a neighborhood of q (respectively from Q through a neighborhood of q) is always defined and controlled. When a tangency is created between invariant manifolds of periodic points there is no recurrence of the tangency to the region of perturbation, opposite to the present setting: we are going to control the creation of a tangency which is recurrent. Another feature of our setting is that we have to ensure that there exist sufficiently many branch of stable manifolds close to q . After all, we obtain a tangency between $W^u(P)$ and a stable manifold not associated to a periodic point.

Remark 3.2. The circle maps in [7], after a convenient reparametrization, have a local form (see [7, Remark 2.2]) given by

$$x \mapsto a + A\theta x + Bx^3 + h.o.t.$$

The reader can realize that the analogy between this formula and that of (H_3) resembles the respective analogy between the quadratic family $x \mapsto 1 - ax^2$ and the Hénon family $(x, y) \mapsto (1 - ax^2 + y, bx)$.

4 Overview of quadratic and Hénon systems

As mentioned before our methodology is based on techniques grounded on works of Benedicks, Carleson, Mora, and Viana [1, 2, 9, 20]. In fact we adapt and extend results present in [7] recreating at some extent the parallels between the one-dimensional quadratic family [1] and the two-dimensional Hénon [2] and Hénon-like [9] families.

We refer the reader to the excellent survey of all these classical arguments present in [8] which encompass a study guide to the original papers.

Although we need to focus on the distinctive features of our setting contrasting with Hénon-like families it is worthwhile recall some of the key aspects of the original arguments. We follow closely [8].

Uniform expansion outside a critical region. A basic result which bounces to Mañé’s works gives uniform hyperbolicity for (pieces of) orbits avoiding neighborhoods of critical points and periodic attractors. First of all we need to define an appropriate *critical region*. These notions are materialized in Section 5.1.1.

Bounded recurrence and non-uniform expansivity. An initial set of parameters is fixed and a concept of “good” parameters is built upon a careful designed control of recurrence of some orbits to the critical region. More precisely, orbits of points in a special set \mathcal{C} are studied aiming two assumptions which must be satisfied for all $n \geq 1$:

(BA) There is an exponentially decreasing (with n) lower bound for the recurrence depth of the n -iterate of such points; and

(FA) There is an exponentially decreasing (with n) frequency of recurrence.

Formalizations of these notions in the cubic setting are presented in Section (5.1.4).

Dynamically defined critical points. In the course of extending the one-dimensional arguments, a highly relevant conceptual point is the non existence of actual critical points for the families (of diffeomorphisms) considered. An original contribution of [2] at this point is to identify tangencies between stable and unstable leaves as natural substitutes for the notion of critical points. At the same time it becomes necessary overwhelm several and new complications. Since the precise formulation of the critical points needs knowledge a priori of the positions of stable leaves, assumption clearly not realistic, the argument has to be settled introducing the auxiliary notion of *finite time critical approximations*. Furthermore, the recovery argument after revisits of some neighborhood of the criticalities must be encompassed this time taking into account geometric complications introduced by the two-dimensional scenario and also the need to satisfy two apparently contradictory forces. On the one hand, we need to have a sufficiently rich set of critical approximations from which one can get inductive information about growth of derivatives. On the other hand, each critical approximation imposes the same parameter exclusion rules related to the depth and frequency of recurrence as present in the one-dimensional case. Section (5.1.2) present the related notion of fields of contractive directions and Section (5.1.3) is devoted to discuss the issues associated to the notion of critical points for families in Section 3.

The induction. We start with an initial interval Ω_0 of parameters and wish to build a positive Lebesgue measure $\Omega = \Omega_\infty$ subset of Ω_0 containing parameters for which

$$(EG) \quad |Df^n(f(z)).(1,0)| \geq e^{cn}, \text{ for all } n \geq 1 \text{ and all } z \in \mathcal{C}.$$

In order to formulate an inductive argument, finite order versions of (BA) , (FA) and (EG) are introduced. So, Ω_n stands for a set of parameters whose associated maps f_a are supposed to inductively satisfy $(BA)_n$, $(FA)_n$ and $(EG)_n$ where these assumptions are formulated for each one of finitely many *critical approximations* of order n in a set \mathcal{C}_n . By excluding some subintervals of Ω_n if necessary we achieve a subset Ω_{n+1} where $(BA)_{n+1}$, $(FA)_{n+1}$ hold for a set \mathcal{C}_{n+1} of critical approximations of order $n+1$. Further it is shown that these two last assumptions imply that $(EG)_{n+1}$ also

holds, recovering the induction hypothesis. To recall a bit more precisely the structure of the arguments, the sets \mathcal{C}_n and \mathcal{C}_{n+1} can be chosen exponentially close in n and so each map f_a with $a \in \Omega_\infty$ is associated to an infinite set of “true” critical points satisfying (EG). See Section 5.1.4 for more details.

Probability of exclusions. As part of the induction argument it is shown that parameters in the same connected component ω of Ω_{n-1} have critical orbits indistinguishable up to time $n-1$ implying distortion bounds of derivatives with respect to phase and parameter spaces which allows to estimate

$$\text{Leb}(\Omega_n) \geq (1 - \epsilon^n) \text{Leb}(\Omega_{n-1})$$

where $0 < \epsilon < 1$ does not depend on n .

5 Arguments in the cubic setting

In the following sections we use a series of small constants which are consistently much larger than b . We use freely the convention of using $C > 1$ as a generic large constant not depending on b . In the same spirit $0 < c < 1$ represents a small constant not depending on b .

5.1 Induction ingredients

5.1.1 The critical region

In this section we establish the constant δ in hypothesis of our families in Section 3.

Recall we define linearizing neighborhoods in Section 3. Let us suppose that x_2 is defined at least in the interval $(-1, 1)$, just in order to simplify notation. Fixed a large integer $N > 0$, there exists $\tilde{\delta} > 0$ such that $\sigma_2^N \tilde{\delta} = 1$. Note that any rectangle $\tilde{S} = [-\tilde{\delta}, \tilde{\delta}] \times [-T, T] \subset \mathcal{U}_2$ remains in \mathcal{U}_2 for N iterates.

Once and for all we fix $\delta = \tilde{\delta}/(10\sigma_1)$ and recall that $R_\delta = [-\delta, \delta]^2$. For N large, $R_\delta \subset \text{int}R_0$ (see H_2 for definition of R_0).

Now, fix $\eta = \delta^2$ in Section 3. It is easy to see from the local form that $\tilde{f}_{a, \delta_0}(R_\delta) \subset \tilde{S}$. So, the assumptions above are compatible with (H_3) .

Hence, the appropriated choice of the constants $N, \delta, \eta, A_1, B_1$, and C_1 , permit us to construct families of diffeomorphisms satisfying hypothesis (H_1) - (H_4) , where $f_{a,\theta}$ preserves the cone of width $1/10$ and expands their vectors at points not in R_δ .

We call R_δ the *critical region*. This is a natural choice since the most dramatic effect of bending on horizontal arcs inside R_0 occurs in a roughly vertical curve passing near q .

Thus, the hypothesis stated on the families presented here yield hyperbolic behavior outside R_δ as claimed in next lemma.

Lemma 5.1. *There is $\sigma_0 > 1$ such that for any family $(f_{a,\theta})$ as above, for any $z \notin R_\delta$ and every norm-1 vector $v = (v_1, v_2)$ with $\text{slope}(v) \leq 1/10$, we have*

$$|\text{slope } Df_{a,\theta}(z) \cdot v| < 1/10$$

and

$$\|Df_{a,\theta}(z) \cdot v\| > \sigma_0.$$

5.1.2 Fields of contractive directions

Again we write $f_{a,\theta}$ as f . The derivative map $Df(z)$ define two orthogonal subspaces $E(z)$ and $F(z)$ on the tangent space T_zM corresponding to the most contracted and the most expanded ones. This is true under mild hypothesis on the non-conformality of $Df(z)$ and is particularly true in our setting.

These direction fields depend smoothly on the point z and are defined on some neighborhood of z as long as the non-conformality of the derivative holds. Integrating these fields we get two orthogonal foliations \mathcal{E} and \mathcal{F} . All this reasoning can be reproduced for $Df^k(z)$, $k \geq 1$, if non-conformality holds. The corresponding sequence of finite order vector fields $E^{(k)}$ and $F^{(k)}$ as well as the finite-order foliations $\mathcal{E}^{(k)}$ and $\mathcal{F}^{(k)}$ can be thought of as finite-versions of classical stable and unstable bundles and manifolds. See [8, Section 2.3] for useful comments on this subject.

Let $1 < n < \nu$ and suppose the contractive fields $E^{(n)}$ and $E^{(\nu)}$ are defined in an open set $U \subset M$. These fields are almost constant and are exponentially close in n . These and other important facts are collected in the next lemma. We write $\mathbf{w}_0 = (1, 0)$ and given $\lambda > 0$ we say that a point $z = (x, y)$ is λ -expanding up to time $n \geq 1$ if

$$\|Df^j(z)\mathbf{w}_0\| \geq \lambda^j, \quad \text{for all } 1 \leq j \leq n.$$

Lemma 5.2 (Contractive fields). *There exists $\tau > 0$ sufficiently small such that if \hat{z} is λ -expanding up to time $n \geq 1$, for some $\lambda \gg b$ and ξ satisfying $\text{dist}(f^j(\xi), f^j(\hat{z})) < \tau^j$ for every $0 \leq j \leq n - 1$ then, for any point z in the τ^n -neighborhood of ξ and for every $1 \leq \ell \leq k \leq n$,*

1. $E^{(k)}(z)$ is uniquely defined and nearly vertical: $|\text{slope}(E^{(k)}(z))| \geq c/\sqrt{b}$;
2. $\text{angle}(E^{(\ell)}(z), E^{(k)}(z)) \leq (Cb)^\ell$ and $\|Df^\ell(z)E^{(k)}(z)\| \leq (C\sqrt{b})^\ell$;
3. $\|D_*E^{(k)}(z)\| \leq C\sqrt{b}$ and $\|D_*^2E^{(k)}(z)\| \leq C\sqrt{b}$;
4. $\|D_*(Df^\ell E^{(k)}(z))\| \leq (Cb)^\ell$;
5. $1/10 \leq \|Df^n(\xi)\mathbf{w}_0\| / \|Df^n(z)\mathbf{w}_0\| \leq 10$;
6. $\text{angle}(Df^n(\xi)\mathbf{w}_0, Df^n(z)\mathbf{w}_0) \leq (\sqrt{C\tau})^n$.

where D_* stands indistinctly for derivatives with respect to z, a or θ .

Proof. Analogous to [2, Section 5.3], [9, Section 7C]. See also [3, Section 2.1], [8, Section 2.3]. \square

Remark 5.3. For future reference, let us point out that we can assume trivially constructed contractive directions in the whole of $f(R)$ of all orders up to some large positive integer N : every $z \in f(R)$ satisfies $\|Df^j(z) \cdot w_0\| \geq \sigma_2^j$ for all $j \leq N$. Indeed this is related to the interval of time while the orbits of points in R remains near the fixed point Q and we can make N as large as we want taking the interval of a -parameters $[-\eta, \eta]$ sufficiently small. Furthermore in the coordinate system introduced in Section 3 these fields coincide with the vertical Euclidean foliation.

5.1.3 Critical points

We use the expression **almost flat curve** to refer to the image of a parametrization $x \mapsto (x_0 + x, y_0 + y(x))$ with y, y', y'' of $\mathcal{O}(\sqrt{b})$.

Let \tilde{z} be the point in $W^u(P) \cap \partial R$ closest to q in $W^u(P)$. We define $G_0 = \text{arc}[P, \tilde{z}]$ in $W^u(P)$ and proceed by induction: once defined G_{n-1} we put $G_n = f(G_{n-1}) \setminus G_{n-1}$.

The set G_n is called the **arc of generation n** .

Given an almost flat curve γ in R we write $t(z)$ for the unit tangent vector to the curve γ in the point z . Naturally there exists some θ' such that if $\theta < \theta'$ then there exists a unique point z which minimizes

$$\angle(t(f(z)), E^{(1)}(f(z))). \quad (7)$$

This is an easy consequence of the cubic nature of the definition of our families (see Section 3).

The same reasoning shows that under similar conditions there exists in G_0 an unique critical approximation $z_0^{(j)}$ of order j for each j from 1 to N . Furthermore in view of Remark 5.3 we know that $z_0^{(j)} = \hat{q}$ for $j \leq N$.

Let us fix $\rho \gg b$ a small positive number and denote by $\gamma(z, \rho)$ the ρ -neighborhood of z in $W^u(P)$. Suppose we have already defined critical approximations $z^{(1)}, \dots, z^{(n-1)}$ in an arc γ of $W^u(P)$ of length at least ρ^n . If in a neighborhood of $f(\gamma)$ we can define the contractive field $E^{(n)}$ then we can formulate the problem of minimizing an expression similar to (7). If this problem have a unique solution, we can define $z^{(n)}$. This effectively works since from Lemma 5.2 we know that the angle between $E^{(n)}$ and $E^{(n-1)}$ is at most $(Cb)^n$ (and $b^n \ll \rho^n$).

When this process can be repeated for all $n \geq 1$ we will eventually define a **limit critical point** z_∞ .

It can be deduced from Lemma 5.2 a natural algorithm to induce critical approximations of arbitrary generation from lower generations ones. Let us consider $\gamma_1 = \gamma(z_1, \ell)$ and $\gamma_2 = \gamma(z_2, \ell)$ arcs of $W^u(P)$ with $\ell \geq \rho^n$. We assume that z_1 is a critical approximation of order n . Hence if $\text{dist}(z_1, z_2) \ll \rho^n$ then it is easy to see that γ_2 also contains a critical approximation of order n .

Notwithstanding the choice of minimizing angles between contracting foliations and unstable manifolds is nothing but a natural one, we have to deal with the lackness of meaning of this notion when θ is very small. Recall that Lemma 5.2 implies that whenever the contractive directions do exist they converge exponentially fast, even with respect to parameters, whereas our local form promotes a fast bending of the unstable manifold while varying θ . So we have to design careful ways of detecting, or preventing, configurations like that shown in Figure 5. This issues will be addressed in Subsection 5.2.

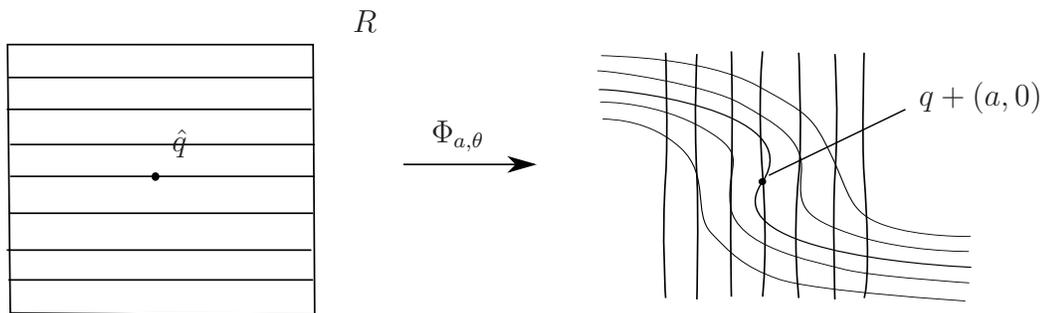


Figure 5: Bad situation

5.1.4 Induction procedure in the cubic setting

We are going to outline some aspects of the induction procedure which are relevant in our context. A substantial part of the arguments in the original works are based solely in the strong dissipativeness of the system and are straightforward applicable to this setting.

As a matter of notation we write $\mathbf{w}_0(z_0) = \mathbf{w}_0$ and

$$\mathbf{w}_n(z_0) = Df^n(f(z_0)) \cdot \mathbf{w}_0(z_0).$$

Let us suppose we have defined for $1 \leq k \leq n$ finite sets \mathcal{C}_k of critical approximations of order k . We collect here some facts that are assumed to be true for each $z_0 \in \mathcal{C}_k$ for a given k .

The generation g of z_0 is much smaller than k and z_0 is the center of an almost flat piece of $W^u(P) \cap R_\delta$ of length at least $2\rho^g$.

We have exponential growth of derivatives:

$$(EG)_k \quad \|\mathbf{w}_j(z_0)\| \geq e^{cj}, \quad 0 \leq j < k.$$

The orbit of z_0 is divided into pieces as follows. Given $0 \leq \nu \leq k$ if $z_\nu = f^\nu(z_0)$ is inside R_δ we say that ν is a **return** time for z_0 . For every such return occurring up to time k we have an associated element $\xi = \xi(z_\nu)$ of \mathcal{C}_k which is called the **bind critical point** of z_ν . We define

$$d_\nu(z_0) = \|z_\nu - \xi\|$$

and assume that

$$(BA)_\nu \quad d_\nu(z_0) > e^{-\alpha\nu}$$

holds and also

$$|\text{slope}(\mathbf{w}_{\nu-1}) - \text{slope}(t(\xi))| \ll d_\nu(z_0). \quad (8)$$

Following a return ν there are p iterates called the **bound period** of z_ν where p is defined in order to maximally satisfy (here h is a constant fixed a priori):

$$\text{dist}(z_{\nu+j}, \xi_j) \leq h e^{-\beta j}, \quad 0 \leq j \leq p.$$

Each bound period starts with a segment called **folding period** with size ℓ satisfying

$$\ell \approx \frac{C}{\log(1/b)} \log(1/d_\nu(z_0)^2) \ll p. \quad (9)$$

Each iterate z_j which is not part of a folding period is said to be a **fold free** iterate. If z_j is fold free then

$$|\text{slope}(\mathbf{w}_{j-1})| \leq C\sqrt{b}.$$

Returns can occur before the end of the bound period of previous returns but bound periods are nested: if ν_1 and ν_2 are successive returns whose bound periods have lengths of p_1 and p_2 iterates respectively and if $\nu_1 + p_1 \geq \nu_2$ then $\nu_2 + p_2 < \nu_1 + p_1$. Returns occurring outside any bound periods are referred to as **free returns**.

If $0 < \nu_1 < \nu_2 < \dots < \nu_m \leq k$ are the free returns of z_0 up to time k and p_j is the length of the bound period associated to the return ν_j then

$$(FA)_k \quad FA(z_0, k) = \sum_1^m p_j \leq \alpha k.$$

Let $\gamma : s \mapsto (x_0 + s, y_0 + y(s))$ be an almost flat curve in the critical region whose image under f is contained in an open set where the contractive field of order k is defined. A tool which is an important part of the arguments is the splitting algorithm which we describe now in an informal way.

While defining the notion of critical approximation of some finite order we considered the action of our dynamical system over almost horizontal arcs in the critical region. Strong dissipativeness of the system and hyperbolicity outside the critical region yields the important geometric fact that the iterates of \mathbf{w}_0 return almost horizontal. But if the parameter θ is very small and n is a return time for z_0 then $\mathbf{w}_n(z_0)$ can be too close to the contractive direction. To estimate the loss of growth we split this vector in the horizontal

direction and the direction of the contractive foliation. The magnitude of the horizontal component is related to the distance $d = d_n(z_0)$ of the return with respect to the binding critical point. In the Hénon-like case this component is of magnitude d^2 . We now proceed to investigate these magnitudes in our context. Recall that we have

$$\Phi_{a,\theta}(x, y) = \begin{bmatrix} a + \sigma_1 y + x(-A_1\theta + B_1x^2 + C_1y^2) \\ -bx + y(-A_2\theta + B_2x^2 + C_2y^2) \end{bmatrix} \quad (10)$$

and

$$D\Phi_{a,\theta}(x, y) = \begin{bmatrix} A(x, y) & B(x, y) \\ C(x, y) & D(x, y) \end{bmatrix}, \quad (11)$$

with

$$\begin{aligned} A(x, y) &= -A_1\theta + 3B_1x^2 + C_1y^2, \\ B(x, y) &= \sigma_1 + 2C_1xy, \\ C(x, y) &= b + 2B_2xy, \text{ and} \\ D(x, y) &= -A_2\theta + B_2x^2 + C_2y^2. \end{aligned}$$

Writing $A(s) = A(\gamma(s))$ and similar expressions for B, C , and D , we have

$$\begin{aligned} A'(s) &= 6B_1s + 2C_1yy', \\ B'(s) &= 2C_1y + 2C_1sy' = 2C_1(y + sy'), \\ C'(s) &= 2B_2(y + sy'), \\ D'(s) &= 2B_2s + 6C_2yy', \\ A''(s) &= 6B_1 + 2C_1((y')^2 + yy''), \\ B''(s) &= 2C_1y' + 2C_1(y' + sy'') = 2C_1(2y' + sy''), \\ C''(s) &= 2B_2(2y' + sy''), \text{ and} \\ D''(s) &= 2B_2 + 6C_2((y')^2 + yy''). \end{aligned}$$

Suppose in a neighborhood of $f(\gamma)$ the existence of the contractive direction of order n and consider the field $\mathbf{e}(s) = \mathbf{e}^{(n)}(s) = (q(s), 1)$, collinear with that direction. We can suppose $|q|, |q'|, |q''|$ bounded by $C\sqrt{b}$. Writing $\mathbf{t}(s) = Df(\gamma(s)) \cdot \gamma'(s)$ it follows that

$$\mathbf{t}(s) = \alpha(s)\mathbf{e}(s) + \beta(s)\mathbf{w}_0. \quad (12)$$

So, the previous estimates imply (the prime means the derivative with respect to s)

$$\begin{aligned}\alpha &= C + Dy, \\ \alpha' &= C' + D'y + D''y, \text{ and} \\ \alpha'' &= C'' + D''y + D'y' + D'y' + Dy''.\end{aligned}$$

It is immediate that $|\alpha|$, $|\alpha'|$, and $|\alpha''|$ are all bounded above by $C\sqrt{b}$. We also have

$$\beta = A + By - \alpha q$$

and so

$$|\beta'(s) - 6C_1s| \leq C\sqrt{b} \quad \text{and} \quad |\beta''(s) - 6C_1| \leq C\sqrt{b}.$$

Now suppose that $\gamma(0)$ is a critical point of order $m \geq k$. Let β be obtained as before from the splitting with respect to k -contractive directions and let us consider also $\tilde{\beta}$ as the corresponding function while splitting with respect to m -contractive directions. It is an easy consequence of Lemma 5.2 that

$$|\beta'(0)| \approx (Cb)^m \quad \text{and} \quad \tilde{\beta}'(0) = 0. \quad (13)$$

Also, in view of (9) we get

$$(Cb)^m \leq d_n(z)^2$$

and hence

$$|\beta(s) - \beta(0)| \approx K_1 d_n(z)^2, \quad (14)$$

for some $K_1 > 1$ large.

Lemma 5.4. *Let n be a return for $z = z_0 \in \mathcal{C}_k$, with $n \leq k$, and let p be the length of the corresponding bound period. Let ξ be the associated binding critical point and $d = \text{dist}(z_n, \xi)$. Then*

$$(a) \quad p \approx \log(1/d)$$

$$(b) \quad \|\mathbf{w}_{n+p}(z_0)\| \geq e^{\tilde{c}(p+1)} \|\mathbf{w}_{n-1}(z_0)\| \quad \text{for some fixed } \tilde{c} > 1.$$

Proof. These facts are derived much in the same way as in [2, Section 7.4] and [9, Section 10]. We outline some steps where estimates are affected by the cubic setting.

We suppose that there is an almost flat curve γ as above with $\gamma(0) = \xi$. For some $\hat{s} \approx d$ we have $\gamma(\hat{s}) = z_n$ and $\gamma'(\hat{s})$ is collinear with $\mathbf{w}_{n-1}(z_0)$ (and almost unitary). In the sequel we write $\mathbf{w}_j(s) = \mathbf{w}_j(\gamma(s))$, for $j \leq n$.

In order to show that in the bound period we have a kind of distortion bound which permits deriving growth of derivatives $\mathbf{w}_j(s)$ from the induction hypothesis of growth of $\mathbf{w}_j(0)$, first one shows that it is possible to write

$$\mathbf{w}_j(s) = \lambda(s)(\mathbf{w}_j(0) + \epsilon(s)), \quad c \leq \lambda(s) \leq C \quad \text{and} \quad \|\epsilon(s)\| \ll \|\mathbf{w}_j(s)\| \quad (15)$$

from which we get

$$\|\mathbf{w}_j(s)\| \approx \|\mathbf{w}_j(0)\| \geq e^{cj} \quad (\text{by induction}).$$

As in (12) we use the contractive field $\mathbf{e} = \mathbf{e}^{(p)}$ of order p , the binding period associated to this return, and write

$$\mathbf{t}(s) = Df(\gamma(s)) \cdot \gamma'(s) = \alpha(s)\mathbf{e}(s) + \beta(s)\mathbf{w}_0. \quad (16)$$

Hence we can estimate how much a point $\gamma(s)$ gets far from its binding point $\xi = \gamma(0)$ in the next iterates by writing

$$f^{j+1}(\gamma(s)) - f^{j+1}(\gamma(0)) = \int_0^s Df^j(f(\gamma(s))) \cdot \mathbf{t}(s) ds$$

and using (16) we get

$$\alpha(s)\mathbf{e}_j(s) + \beta(s)\mathbf{w}_j(s) = \alpha(s)\mathbf{e}_j(s) + (\beta(s) - \beta(0))\mathbf{w}_j(s) + \beta(0)\mathbf{w}_j(s),$$

with subscripts j meaning the obvious iterate under action of Df .

In particular, for $j = p$, since $\mathbf{e}(s)$ is exponentially contracted for p iterates we know that the integrand in the first term on the right hand side is of magnitude less than $(Cb)^p$. From (14) and writing $\hat{\Theta} = \beta(0)$ we get the estimate

$$e^{-\beta p} \approx \text{dist}(z_{n+p}, \xi_p) \approx \|\mathbf{w}_p(0)\| (\hat{\Theta}d + K_2d^3),$$

with $K_2 = (1/3)K_1$. Taking into account the definition of p and that $\|\mathbf{w}_p(0)\| \geq e^{cp}$ we get

$$e^{-\beta(p+1)}e^{-c} \leq e^{cp}(\hat{\Theta}d + K_2d^3) \leq e^{-\beta p}. \quad (17)$$

Remark 5.5. Note that more rigorously we must write $\widehat{\Theta} = \beta(\tilde{s})$ where $\beta'(\tilde{s}) = 0$, but since $|\tilde{s}| \leq (Cb)^p$ we have $|\beta(0)| \approx |\beta(\tilde{s})|$ and $d \approx s \approx \tilde{s}$.

We now use the fact that $\widehat{\Theta} > 0$ along all our construction, as will be explained in Section 5.2. The last result gives easily item (a). Furthermore the second inequality in (17) gives

$$e^{cp}K_2d^3 \leq e^{-\beta p}$$

which implies

$$\frac{1}{d} \geq e^{\frac{1}{3}(c+\beta)p} K_2^{\frac{1}{3}}.$$

From here and the first inequality in (17) we get

$$e^{cp}(\widehat{\Theta} + K_1d^2) \geq e^{-\beta(p+1)}e^{-c}e^{\frac{1}{3}(c+\beta)p}K_2^{\frac{1}{3}}. \quad (18)$$

On the other hand note that

$$\frac{\|\mathbf{w}_{n+p}(z_0)\|}{\|\mathbf{w}_{n-1}(z_0)\|} \geq (1 + C\sqrt{b}) \|Df^{p+1}(\gamma(\hat{s})) \cdot \gamma'(\hat{s})\| \quad (19)$$

and exploring again (16) we get

$$\|Df^{p+1}(\gamma(\hat{s})) \cdot \gamma'(\hat{s})\| \geq |\beta(0)| \|\mathbf{w}_p(0)\| - C\sqrt{b}(Cb)^p \quad (20)$$

and we also have

$$|\beta(0)| \approx \widehat{\Theta} + K_1d^2 \quad \text{and} \quad \|\mathbf{w}_p(0)\| \geq e^{cp}.$$

Combining (18),(19) and (20) we get immediately item (b). \square

Remark 5.6. We can derive exponential growth of $\mathbf{w}_k(z_0)$ by observing that

$$\|\mathbf{w}_k(z_0)\| = \prod_{i=1}^k \frac{\|\mathbf{w}_i(z_0)\|}{\|\mathbf{w}_{i-1}(z_0)\|}.$$

For each $n \leq k$ a (free) return time with corresponding bound period p we have

$$\prod_{i=n}^{n+p} \frac{\|\mathbf{w}_i(z_0)\|}{\|\mathbf{w}_{i-1}(z_0)\|} = \frac{\|\mathbf{w}_{n+p}(z_0)\|}{\|\mathbf{w}_{n-1}(z_0)\|} \geq 1$$

according to the previous lemma and

$$\prod_{i=n+p+1}^{\nu} \frac{\|\mathbf{w}_i(z_0)\|}{\|\mathbf{w}_{i-1}(z_0)\|} = \frac{\|\mathbf{w}_\nu(z_0)\|}{\|\mathbf{w}_{n+p}(z_0)\|} \geq e^{c\mu}$$

where ν is the next free return after n and $\mu = \nu - (n + p + 1)$ and this last estimate follows from the results in Section 5.1.1. Those parameters satisfying the induction hypothesis in particular obey $(FA)_k$ and this gives the expected growth.

5.2 Creation of tangencies in a controlled way

We write $\mathcal{R} = [-\eta, \eta] \times [-1, \epsilon]$ for the (a, θ) -parameter space. Recall that in the one dimensional case (see [7]) we deal with curves at the parameter space which can be described by maps $a \mapsto (a, \tilde{\theta}) \in \mathcal{R}$, for $\tilde{\theta}$ fixed, and apply the *exclusion parameter arguments* (which we will denote as EPA from now on) to them. Here we generalize this notion.

Definition 5.7. A θ -flat curve is the graph in \mathcal{R} of a smooth map $[-\eta, \eta] \rightarrow [-1, \epsilon]$, which has all derivatives up to order 3 bounded by $C\sqrt{b}$.

Note that it is possible to extend easily the arguments and apply EPA to θ -flat curves.

We also want to introduce a notion which will indicate how far we are from “forming tangencies”. Let Υ be a θ -flat curve as above. While applying EPA to this curve, let $(a, \theta) \in \Upsilon$ be a parameter that has not been excluded up to time j . In the context of the arguments we are dealing with among several facts this means that there exists a finite set \mathcal{C}_j of critical approximations of order j associated to the map $f_{a,\theta}$ and each one of these critical approximations lies on a sufficiently large and flat arc of $W^u(P_{a,\theta})$. Moreover around the images of these arcs there are well defined maximal contractive directions of order j . Since the critical approximations are defined intrinsically as minimizing the angles between W^u and the contractive foliations (see (7)), we can define

$$\angle_j(a, \theta) = \min\{\angle(t(\xi), \Gamma^j(f(\xi)) ; \xi \in \mathcal{C}_j\}.$$

where $\Gamma^j(\cdot)$ is the leave of the contractive foliation passing through the specified point.

We fix a small number ϱ , but satisfying $\varrho \gg b$. Given $m > 1$ it follows from Remark 5.3 and Section 5.1.3 that for each $1 \leq j \leq N$ there exists a θ -flat curve Υ_j^m in \mathcal{R} satisfying,

$$\angle_j(a, \theta) = \varrho^m \quad \text{for } (a, \theta) \in \Upsilon_j^m.$$

Remark 5.8. In fact θ is constant over Υ_j^m , for $j \leq N$.

Remark 5.9. While discussing the splitting algorithm in Section 5.1.4 in a number of places we have assumed that the minimum value of $\beta(\cdot)$ along an almost flat curve passing through a critical point (of finite order) was attained at that point with an associated value denoted by $\widehat{\Theta}$. The context presented now justify why we could assume $\widehat{\Theta} > 0$.

Note that if (a, θ) was not excluded up to time j then for each $(\tilde{a}, \tilde{\theta})$ sufficiently close we also have the j -contractive field defined and the local form (see Section 3) gives

$$\left| \angle_j(a, \theta) - \angle_j(\tilde{a}, \tilde{\theta}) \right| \leq c_1 \sqrt{b} |a - \tilde{a}| + C_2 \left| \theta - \tilde{\theta} \right|. \quad (21)$$

In particular we get a family of θ -flat curves

$$\{\Upsilon_N^m\}_{m \geq 1}$$

in \mathcal{R} satisfying, $\angle_j = \varrho^m$.

Let us introduce some notations. While applying EPA to Υ_j^m we get a collection $\Omega_k = \Omega_k(j, m)$ of subsets of Υ_j^m satisfying

$$\Upsilon_j^m = \Omega_0 \supset \Omega_1 \supset \Omega_2 \cdots \supset \Omega_k \supset \cdots$$

Each Ω_k is an union of subarcs ω of Υ_j^m collected in a partition $\mathcal{P}_k = \mathcal{P}_k(j, m)$ of this curve.

For each $m > N$ we want to exhibit a θ -flat curve $\Upsilon^m = \Upsilon_m^m$ such that $\angle_j(a, \theta) \approx \varrho^m$ for all $(a, \theta) \in \Omega_j(m) := \Omega_j(m, m)$, that is to say, for all $(a, \theta) \in \Upsilon^m$ not excluded by EPA up to time j . Here the scale \approx is chosen to precludes presence of tangencies and will be made precise in a little while.

The curve Υ^m will be constructed from Υ_N^m by applying EPA a finite number of times and a **correction procedure** (to be detailed) in order to get

$$\Upsilon_N^m \rightsquigarrow \Upsilon_{N+1}^m \rightsquigarrow \Upsilon_{N+2}^m \rightsquigarrow \cdots \rightsquigarrow \Upsilon_{m-1}^m \rightsquigarrow \Upsilon_m^m = \Upsilon^m$$

We describe this construction and formulate precisely the correction procedure inductively. Suppose we have just constructed Υ_j^m , with $N \leq j \leq m - 1$ satisfying:

$$|\angle_j(a, \theta) - \varrho^m| \leq (Cb)^j \quad \text{for all } (a, \theta) \in \Omega_j(j, m) \quad (22)$$

By induction we are able to apply the induction of EPA to Υ_j^m up to time j . For each $1 \leq k \leq j$ the partition $\mathcal{P}_k = \mathcal{P}_k(j, m)$ of subarcs ω of Υ_j^m is obtained first refining \mathcal{P}_{k-1} and then throwing away some of its arcs by the exclusion rules of EPA. Let ω be one of the arcs of \mathcal{P}_j . In the most general case there is a sub-arc $\omega_{exc} \subset \omega$ which must be excluded while passing from time j to $j + 1$. Let ω' be a connected component of $\omega \setminus \omega_{exc}$. Note that on ω' by definition we have

$$|\angle_j - \varrho^m| < (Cb)^j \quad (23)$$

and by Lemma 5.2

$$|\angle_{j+1} - \angle_j| < (Cb)^j \quad (24)$$

We claim that near ω' we can find another arc of θ -flat curve ω'' on which we have

$$\angle_{j+1} = \varrho^m \quad (25)$$

This can be deduced from the following facts. The contractive directions are $(C\sqrt{b})$ almost constant with respect to the phase and parameter space (see Lemma 5.2) where they are defined. Also the dynamics of $f(a, \theta, z)$ and $f(\tilde{a}, \tilde{\theta}, \tilde{z})$ are indistinguishable up to time $j + 1$ if the distance between (a, θ, z) and $(\tilde{a}, \tilde{\theta}, \tilde{z})$ is at most of order $C(\sqrt{b})^{j+1}$ and, in view of (21), for compensating the terms of $\mathcal{O}(b^j)$ in (24) we only need to perturb θ in a order of magnitude less than $\mathcal{O}(b^j)$.

Finally, we define Υ_{j+1}^m as a θ -flat curve containing each one of those corrected arcs. In order to be more precise about the existence of such a curve we recall that each ω_{exc} has length of order of $Ce^{-\alpha j}$ which is \gg than the distance from ω' to its corrected version ω'' . Note also that for each arc of $\mathcal{P}_{j+1}(j + 1, m)$ we can not be sure that (25) still holds but the same arguments above give surely that

$$|\angle_{j+1} - \varrho^m| \leq (Cb)^{j+1}$$

which recovers exactly the induction hypothesis of (22).

Note that this strategy yields a θ -flat curve $\Upsilon^m = \Upsilon_m^m$ satisfying

If $(a, \theta) \in \Omega_k(m)$, $k \geq m$ then $|\angle_k(a, \theta) - \varrho^m| < (Cb)^m \ll \varrho^m$.

Hence for each (a, θ) in the positive Lebesgue measure set $\Omega_\infty(m)$ we have

$$0 < |\angle_\infty(a, \theta)| \approx \varrho^m.$$

6 Proof of Theorem 1

In the previous section we construct subsets $\Omega_\infty(m)$ of the parameter space. According to Definition 5.7 and since the curves Υ^m and Υ^{m+k} are exponentially close on m for all k , we conclude that the family of smooth functions on $[-\eta, \eta]$ whose graphs correspond to the family of curves $(\Upsilon^m)_m$ converge uniformly to a continuous function and so it is well defined the limit

$$\widehat{\Omega}_\infty = \lim_m \Omega_\infty(m).$$

The construction of each set $\Omega_\infty(m)$ is based on the exclusion parameters argument whose one of the most relevant feature is that each such final set has positive measure and, in fact, similar to [7], the construction is uniform on θ -parameters and so the measures of $\Omega_\infty(m)$ are uniformly bounded away from zero, for all m . These considerations yields the conclusion that $\widehat{\Omega}_\infty$ has positive measure.

The main feature of a parameter $(a, \theta) \in \widehat{\Omega}_\infty$ is the non hyperbolicity of the correspondent map $f_{a,\theta}$: there is a point \hat{z} in $W^u(P)$ such that the tangent direction of $W^u(P)$ at \hat{z} is mapped by the derivative of $f_{a,\theta}$ on a contractive direction. So, it can not be hyperbolic once a direction is both forward and backward exponentially contracted. Thus, each parameter $(a, \theta) \in \widehat{\Omega}_\infty$ corresponds to a non hyperbolic map $f_{a,\theta}$. By construction, $\widehat{\Omega}_\infty$ is accumulated by $\Omega_\infty(k)$. The fact that $f_{a,\theta}$, $(a, \theta) \in \widehat{\Omega}_\infty$, is accumulated by hyperbolic maps $f_{a_k, \theta(a_k)}$, $(a_k, \theta(a_k)) \in \Omega_\infty(m)$ (see Corollary 6.2) implies that $f_{a,\theta}$ belongs to the boundary of \mathcal{H} .

In order to prove Theorem 1 we show in Corollary 6.4 the hyperbolicity of periodic points of $f_{a,\theta}$, $(a, \theta) \in \widehat{\Omega}_\infty$.

In Proposition 6.5, we show the existence of a positive measure subset of $\widehat{\Omega}_\infty$ such that the unstable manifold of P is tangent to a stable manifold not associated to periodic points.

From here we get that every point in the neighborhood \mathcal{U} of Λ (see Section 3) expands the horizontal direction:

Proposition 6.1. *Let (a, θ) be in $\Omega_\infty(m)$, $m \geq N$. There exists $\hat{c} > 0$ and $\sigma > 1$ such that for every $z \in \mathcal{U}$, we have*

$$|Df_{a,\theta}^k(z) \cdot (1, 0)| \geq \hat{c}\sigma^k.$$

Proof. Analogous to [7, Proposition 7.1]. □

Corollary 6.2. *For all (a, θ) in $\Omega_\infty(m)$, $m \geq N$, the map $f_{a,\theta}$ is (uniformly) hyperbolic.*

Proof. Recall that the expansion of some direction besides the global strong dissipativeness of $f_{a,\theta}$ imply the existence of a $Df_{a,\theta}$ invariant splitting of the tangent space of the neighborhood of \mathcal{U} in contractive and expanding subbundles. □

Proposition 6.3. *Let (a, θ) be in $\widehat{\Omega}_\infty$. For (Lebesgue) almost every $z \in \Lambda_{a,\theta}$, including all periodic points,*

$$\lambda_{\inf}(z) = \liminf_{n \rightarrow \infty} \frac{1}{n+1} \log |Df_{a,\theta}^n(z) \cdot (1, 0)| > 0.$$

Proof. Analogous to [7, Proposition 7.2]. □

Corollary 6.4. *Let (a, θ) be in $\widehat{\Omega}_\infty$. All periodic point of $f_{a,\theta}$ are (uniformly) hyperbolic.*

Proof. The fact that the orbit of a periodic point is finite associated to the claim of the previous proposition gives the expansion of the derivative along the horizontal direction. Again, by the strong dissipativeness of the jacobian, it follows the existence of a contractive direction. □

Finally, we prove the existence of a positive measure subset where Theorem 1 holds.

Proposition 6.5. *There is a positive measure subset $\widehat{\mathcal{A}}$ of $\widehat{\Omega}_\infty$ such that for all (a, θ) in $\widehat{\mathcal{A}}$ there exists a stable manifold W^s of $f_{a,\theta}$ not associated to a periodic point such that $W^u(P)$ and W^s are tangent.*

Proof. It follows from the control of recurrence of each critical orbit that all critical points are non periodic. In particular, the point of tangency $t = t_{a,\theta}$, $(a, \theta) \in \widehat{\Omega}_\infty$ is non periodic.

Moreover, if the tangency point t belongs to a stable manifold of a periodic point, then for each neighborhood $B(t)$ fixed, there are a finite number of forward iterates inside $B(t)$.

Due the hyperbolicity outside a fixed neighborhood of t and the bounded distortion between phase space and parameter space, we have that the set of parameters such that the forward orbit of the tangency point goes into B just a finite number of time has zero measure. For n large enough, let \mathcal{B}_n be the set of parameters such that the forward tangency orbit never goes to the ball of radius $1/n$ centered in t . Note that the set of parameters such that the tangency orbit belongs to a stable manifold of a periodic orbit is contained in $\cup \mathcal{B}_n$ which has zero measure. Hence, the subset of $\widehat{\Omega}_\infty$ whose tangency belongs to a periodic point has zero measure. This proves the proposition. \square

To conclude the proof of Theorem 1, take

$$\mathcal{A} = \left\{ a \in [\eta, -\eta] : (a, \theta) \in \widehat{\mathcal{A}} \right\}.$$

Since $\widehat{\mathcal{A}}$ is a limit set of positive measure subsets of $\Omega_\infty(m)$ whose measures are uniformly bounded away from zero and these sets are θ -flat curves, we conclude that \mathcal{A} has positive measure, finishing the proof of Theorem 1.

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Vanderlei Horita (vhorita@ibilce.unesp.br)
Departamento de Matemática, IBILCE/UNESP
Rua Cristóvão Colombo 2265
15054-000 S. J. Rio Preto, SP, Brazil

Nivaldo Muniz (nivaldomuniz@gmail.com)
Departamento de Matemática, UFMA
Avenida dos Portugueses, S/N
65000-000 São Luís, MA, Brazil

Paulo Rogério Sabini
Instituto de Matemática e Estatística, UERJ
Rua São Francisco Xavier, 524
20550-900 Rio de Janeiro, RJ, Brazil